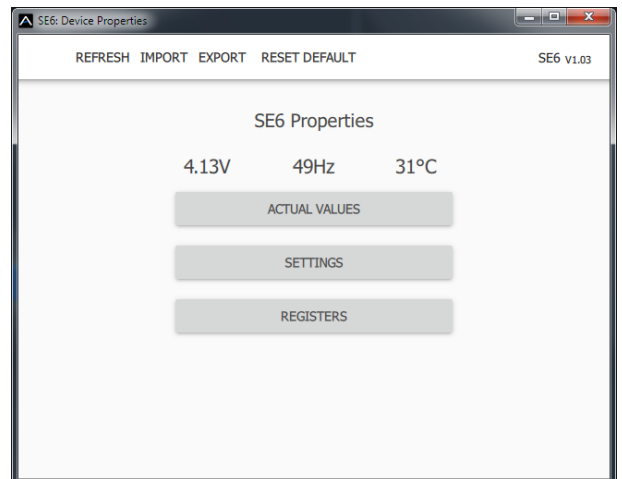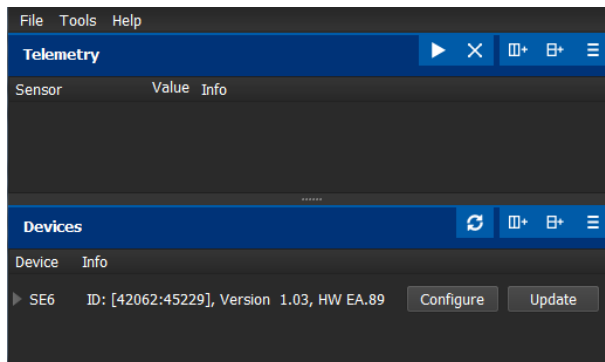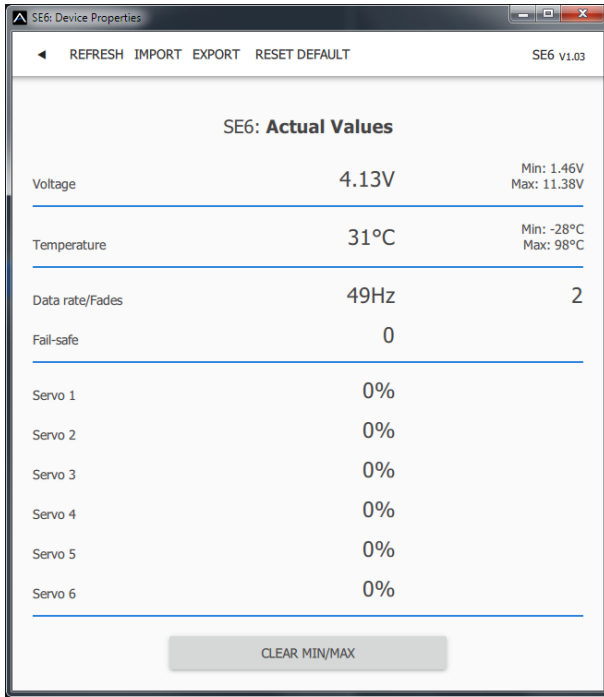# SE6 Release Notes

Version 1.04 *(April 2024)*

- FrSky: Introduced compatibility with FPort and FBus capable receivers. The SE6 receives and decodes servo positions from the data stream. The device is able to decode all channel data (from FBus 8 up to FBus 24), only the first 16 channels may be assigned to the servo outputs.
- FrSky: The SE6 only reads the serial data from the receiver. It does not send any telemetry or configuration back, so the optional channel assignment has to be done using the MAV Manager software. It is possible to combine multiple SE4s and SE6s on a single bus.
- Frsky and Futaba SBus: Improved channel position matching, so that the servo positions at SE6 outputs are equal to the corresponding receiver outputs.
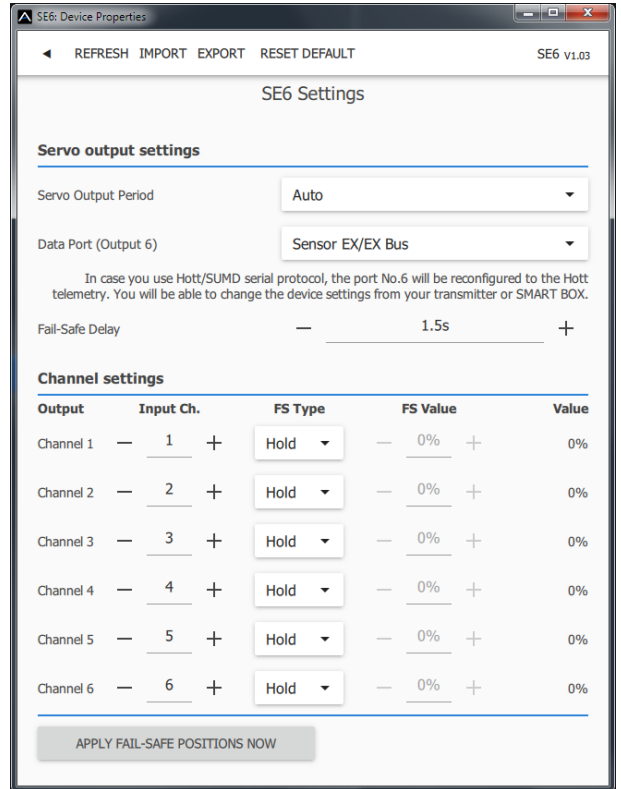
Version 1.03

- Improved compatibility with JETI EX Bus 24-channel mode.
- Added PowerBox P²Bus support on the Rx input, including telemetry (voltage/temperature).
- PC Configuration support using the MAV Manager software has been implemented. Use MAV Manager version 1.6.0 or later.

Actual telemetry values

SE6 Configuration

VERSION 1.02

- Not released to public.

VERSION 1.01

- Initial version.